

2<sup>nd</sup> IWGoRS workshop  
Masaryk's College  
Prague



## Free field rotations: Relevance on buildings in near field

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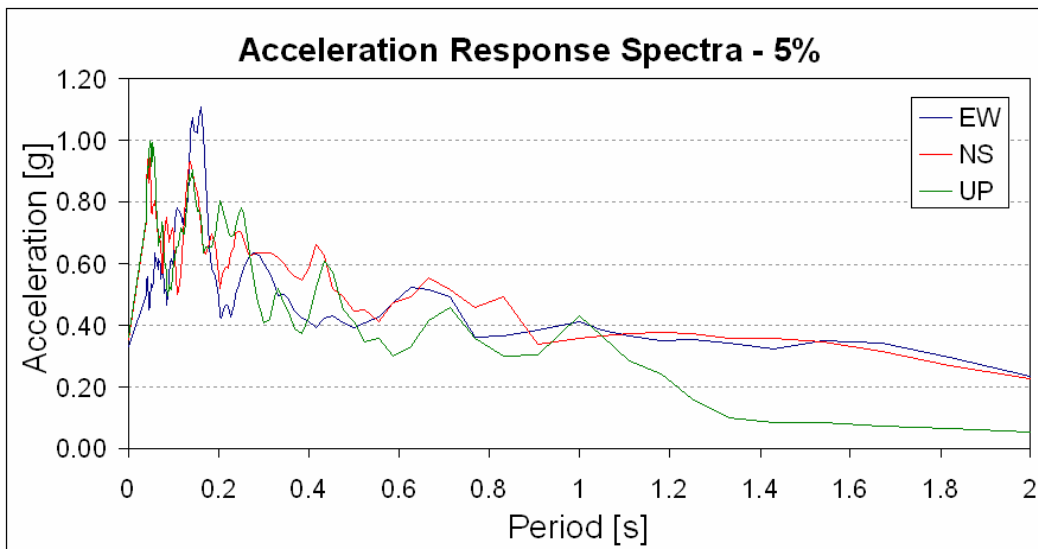
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## Free field rotations: relevance on buildings in near field

- Introduction
- Measure of rotations
- Rotational accelerograms
- A civil engineering application
- Conclusions

## Focus on

- Soil rotation around horizontal axes, during an earthquake
- Evaluation of rotation accelerations
- Relevance of this input motion for relatively tall structures, with reference to the horizontal motion
  - **Coherency** model
  - **Relative importance** of the vertical to the horizontal input motion



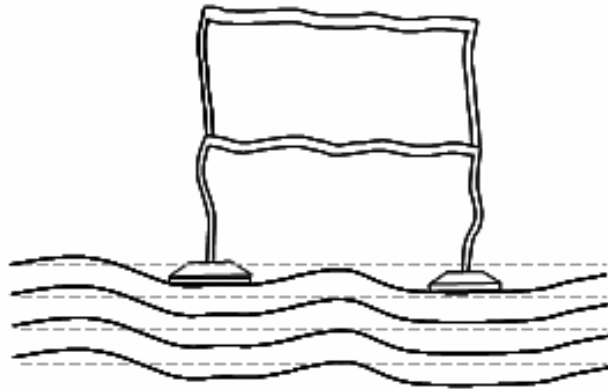
Comparison between the Response Spectrum of vertical motion and that of horizontal motions (EW and NS direction).

Earthquake event of L'Aquila, Italy (April 6<sup>th</sup>, 2009)

## Focus on

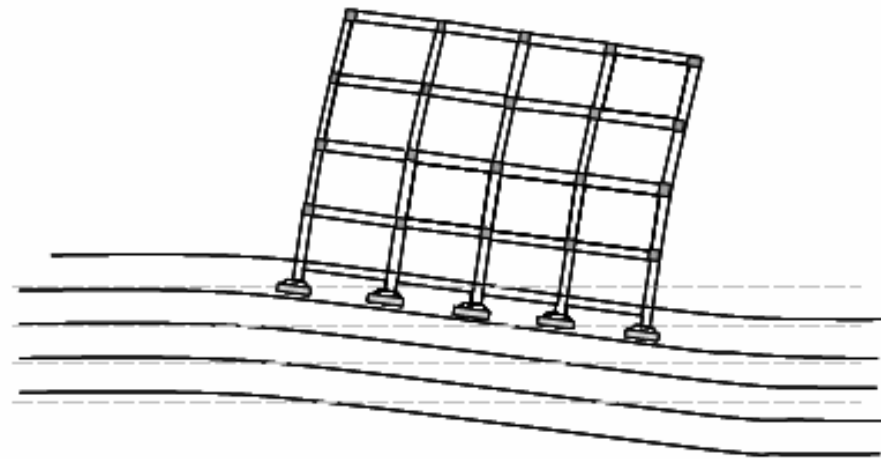
- Effects of rotational motion on engineering structures

## High frequency content



- Local vibration of beams and columns
- Meaningless motion of the building center of mass

## Low frequency content



- Overturning moment
- Horizontal displacement of the center of mass
- **Higher stress in structural element**

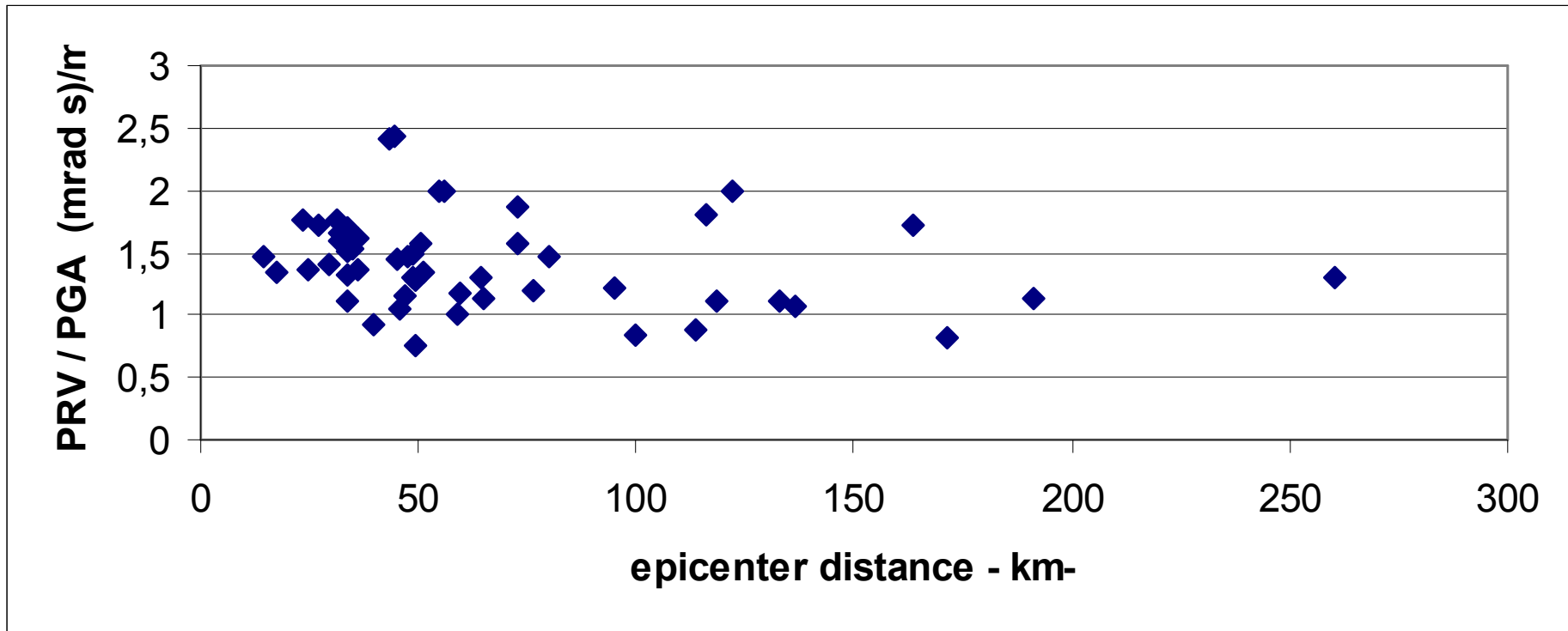
## Direct measure

- Rotational ground motions have not been observed directly until the last decade
- **Rotation-sensitive instruments** have been developed to provide the evaluation of the rotation at a point

## Indirect measure

- Rotations obtained through records collected by **closely spaced arrays** of strong motion accelerometers
- Spatial distribution of the translation described through the **Cross Power Spectrum of translations**
- **Mathematical relationship** between the Cross Power Spectrum and the Power Spectrum of rotations

## Direct measure

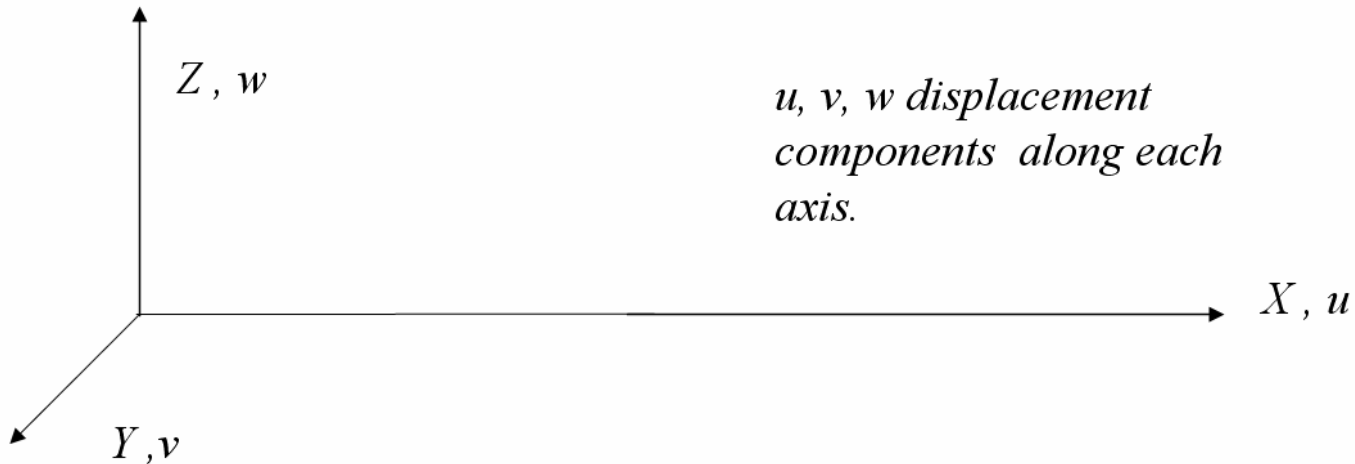


*Data presented by Liu et al. 2009. Ratio between the peak rotation velocity PRV, and the peak horizontal acceleration PGA, in  $\text{mrad} \times \text{s}/\text{m}$ . Average value 1.43.*

## Power Spectrum of Rotations

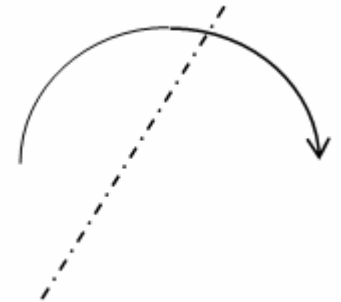
Mathematical relationship between the rotational power spectrum and the cross power spectrum simultaneously registered in an array

### Definitions

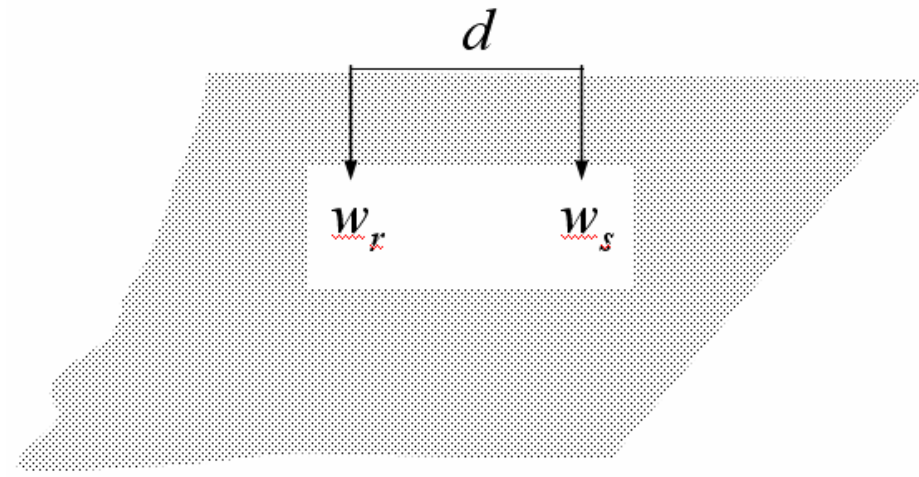


- Rotation around the y-axis

$$\psi_y = \frac{1}{2} \left( \frac{\partial w}{\partial x} - \frac{\partial u}{\partial z} \right)$$



- Cross-Power Spectrum of 2 vertical signals  $w_r, w_s$  at distance  $d$



$$S_w(\omega, d) = \lim_{T \rightarrow \infty} E \left( \frac{2}{T} [W_r(\omega) \times W_s^*(\omega)] \right)$$

$$\begin{cases} W_r(\omega) = \int_0^T w_r(t) e^{-i\omega t} dt \\ W_s(\omega) = \int_0^T w_s(t) e^{-i\omega t} dt \end{cases}$$

- Coherency function  
[Abrahamson et al, 1985]

$$\gamma_w(\omega, d) = \frac{S_w(\omega, d)}{S_w(\omega, 0)}$$

- Average rotation between 2 points  $r$  and  $s$  separated by distance  $d$

$$\psi_d(t) = \frac{w_r(t) - w_s(t)}{d}$$

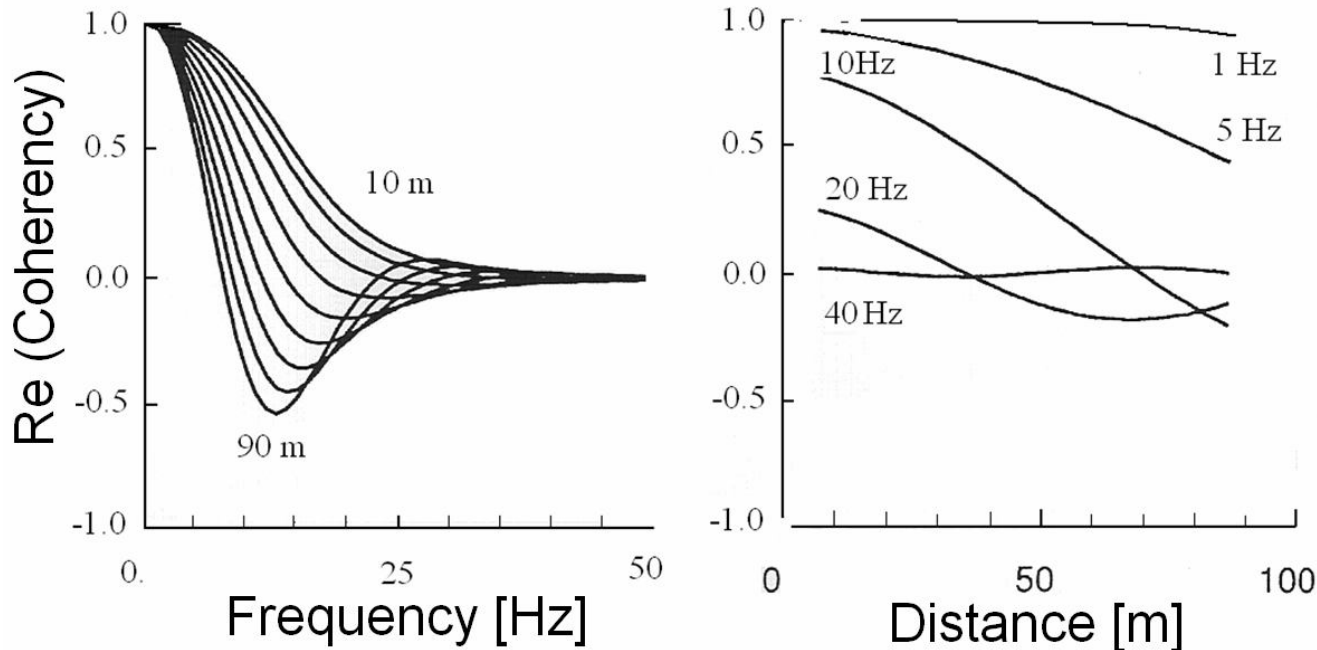


- Power Spectrum of rotation

$$S_{\psi}(\omega, d) = \frac{2S_w(\omega, 0)}{d^2} \left(1 - \text{Re}[\gamma_w(\omega, d)]\right)$$

- Power Spectrum of rotation at a point

$$S_{\psi}(\omega, 0) = \lim_{d \rightarrow 0} S_{\psi}(\omega, d)$$



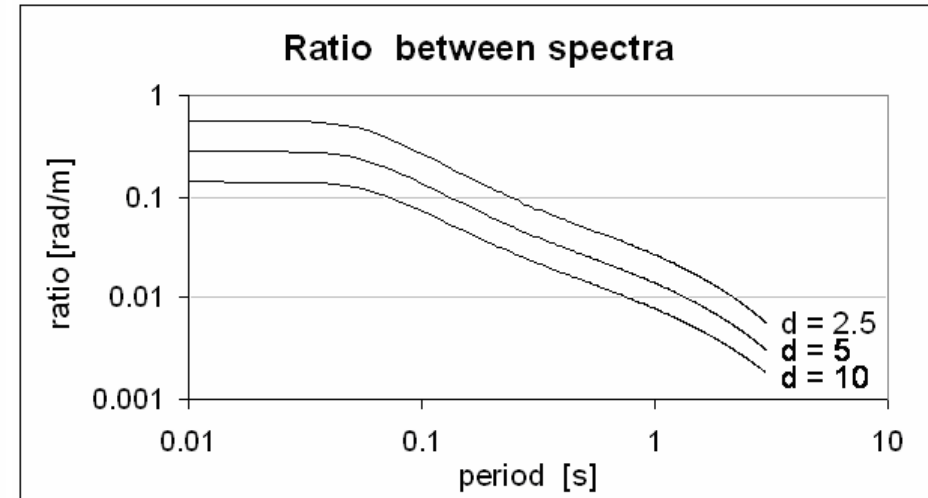
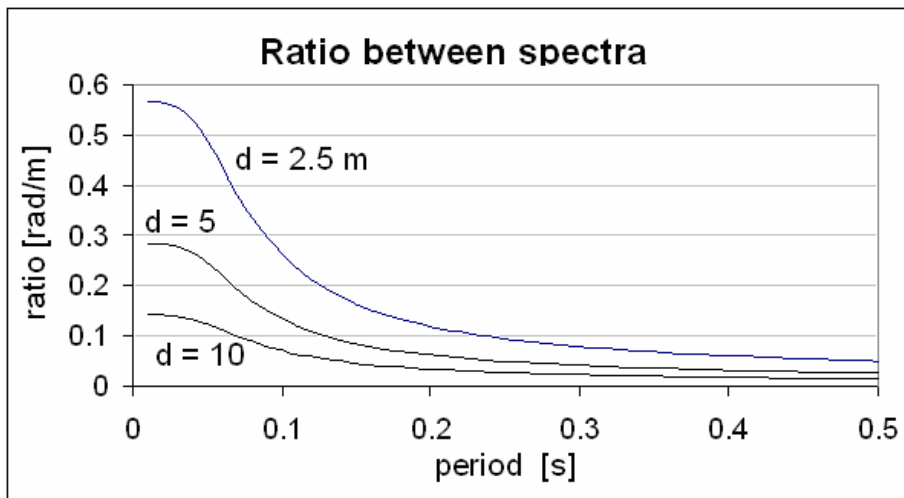
Real part of coherency, function of frequency and inter-station separation.  
Records of accelerations.

[Abrahamson et al, 1991]

## Dependence of the measurements on the separation $d$

- The ratio between power spectra tends to 0 for increasing periods
- The cross power spectrum between closely-spaced stations depends on separation between stations  $d$
- Rotation of mass-less rigid foundation assumed to be related to a rotation averaged over a separation comparable to the block dimensions

$$\sqrt{\frac{S_{\psi}(\omega, d)}{S_w(\omega, 0)}}$$



## Rotational accelerogram from measured vertical accelerogram

- Ground rotational acceleration records few and affected by noise with uncertainties
- Evaluation of rotational accelerogram on the basis of the relationship between rotational and vertical spectra

## Input vertical ground acceleration written as Fourier series

$$w = \sum_1^N a_i \cos(\omega_i t + \varphi_i) = a_1 \cos(\omega_1 t + \varphi_1) + a_2 \cos(\omega_2 t + \varphi_2) + \dots$$

$$\dots + a_i \cos(\omega_i t + \varphi_i) + \dots + a_N \cos(\omega_N t + \varphi_N).$$

$$\omega_1 = \frac{2\pi}{T} \text{ rad/s}, \omega_2 = 2 \times \omega_1, \dots, \omega_i = i \times \omega_1, \dots, \omega_N = N \times \omega_1$$

- Input **vertical power spectrum**, defined at discrete points  $\omega_i$

$$S_w = \left( \frac{a^2}{d\omega} \right) = a^2 \frac{T}{2\pi}$$

## Output rotational acceleration written as Fourier series

- Relationship between rotational and translational power spectrum, defined at discrete points  $\omega_i$ . Ulagged-coherence method by Abrahamson

$$S_{\psi} = \frac{2S_w}{d^2} (1 - cohe(\omega, d))$$

- Rotational accelerogram

$$\psi(t) = \sum_0^N h_i \cos(\omega_i t + \varphi'_i)$$

with:

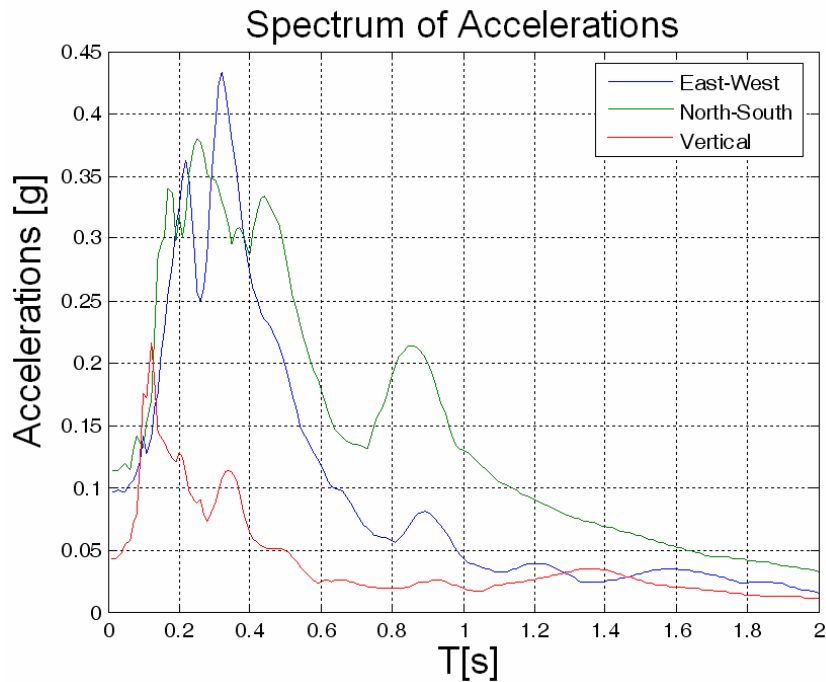
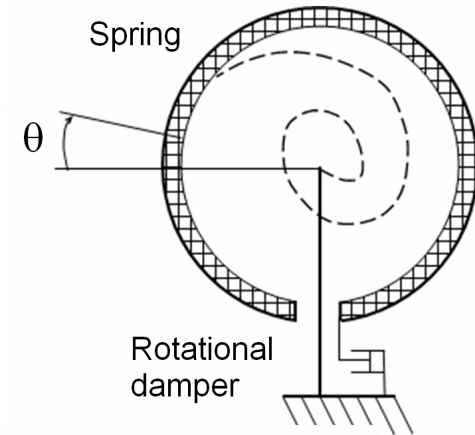
$$h_i = \sqrt{S_{\psi} \cdot d\omega} = \sqrt{S_{\psi} \cdot \frac{2\pi}{T}}$$

## Phase factors

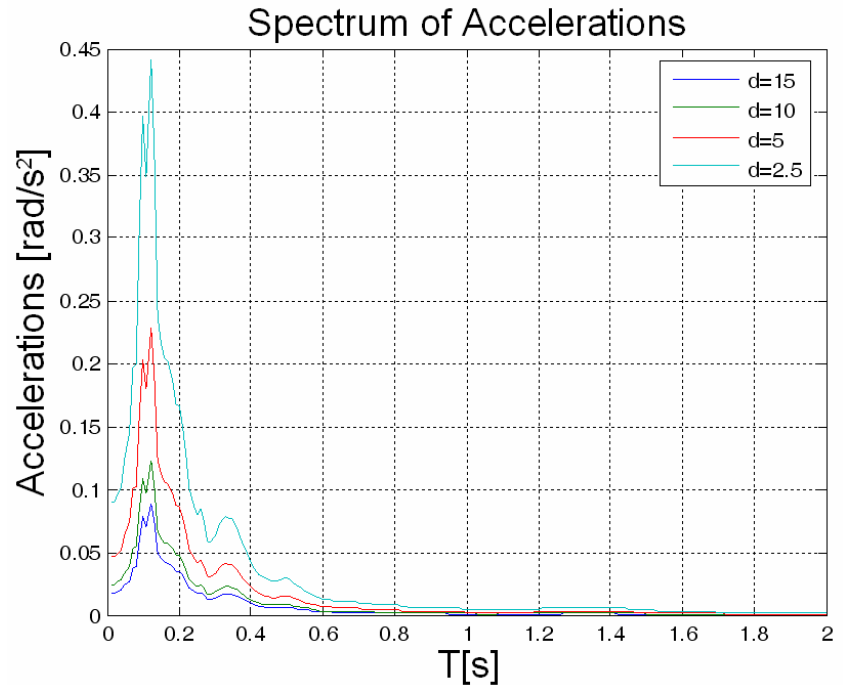
- Same factors of the vertical component
- Peak values in correspondence with input vertical ground acceleration peaks

## Definition of Rotational Response Spectra

- For a one degree of freedom oscillator, it represents the peak rotational acceleration of the oscillator, during the earthquake duration



Translational Response Spectra  
Taiwan SMART1(5)C00 29/01/1981



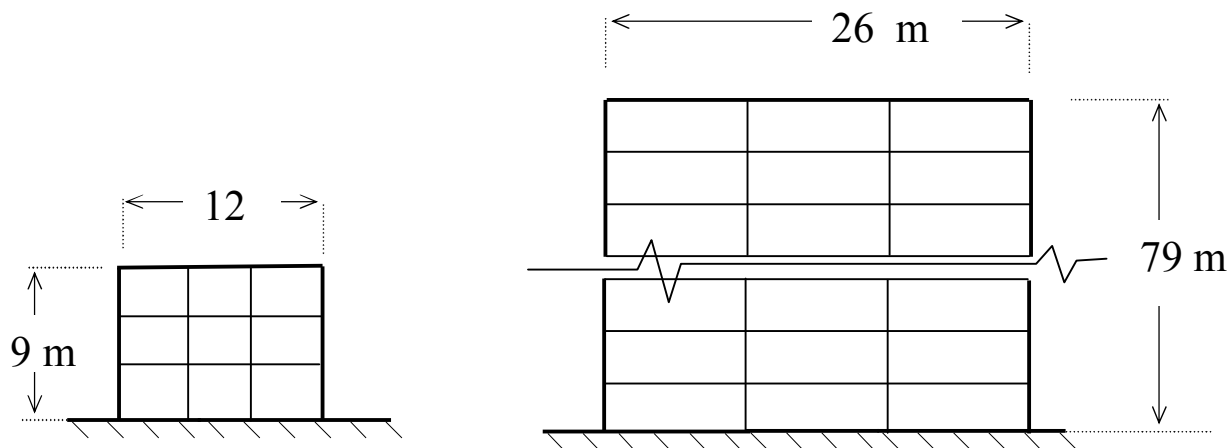
Rotational Response Spectra,  
varying the value of separation  $d$

## Aim

- Illustrate the relevance of rotational input motions with respect to the effects of horizontal excitations consistent with them

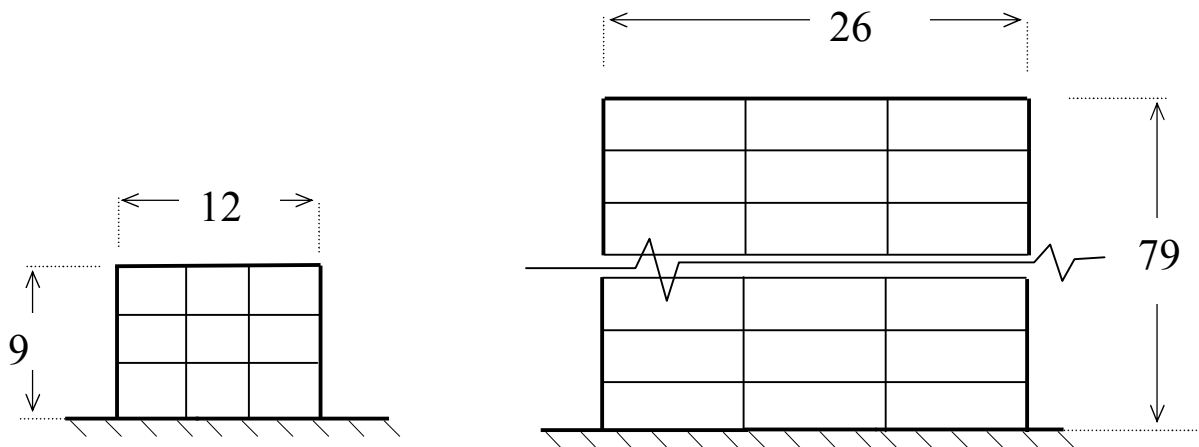
## Assumptions

- Free field rotation applied to the foundation without modification from reaction forces, disregarding soil compliance
- Rotation estimate according to a separation  $d$ , suitable to represent the global effects on the building



## Model

- Identical mathematical model applied in the analysis of the translational and rotational excitation
- Two simple 2D model buildings, of a moment-resisting structural type
  - Reinforced concrete three stories structure (*First natural period  $T=0.48$  s*)
  - Steel twenty stories structure (*First natural period  $T=1.56$  s*)



## Results

- Evaluation of the **relative incidence** (in percentage) of the rotational component to the translational one, on the basis of the roof horizontal displacement
- Several analysis considering different **real earthquakes** (*referring to Taiwan SMART1(5) and Taiwan SMART1(33)*)

|                        |        | Rotational Component Incidence [%] |       |             |       |
|------------------------|--------|------------------------------------|-------|-------------|-------|
|                        |        | East-West                          |       | North-South |       |
|                        | Frame  | Max                                | Min   | Max         | Min   |
| Taiwan SMART1(5): C00  | 3 x 3  | 1.37                               | 1.52  | 0.96        | 1.27  |
|                        | 20 x 3 | 21.63                              | 17.52 | 9.39        | 9.09  |
| Taiwan SMART1(5): O01  | 3 x 3  | 1.50                               | 1.67  | 0.61        | 0.65  |
|                        | 20 x 3 | 11.65                              | 12.2  | 5.54        | 6.07  |
| Taiwan SMART1(33): C00 | 3 x 3  | 1.57                               | 1.91  | 1.60        | 1.78  |
|                        | 20 x 3 | 14.30                              | 18.51 | 12.07       | 13.83 |
| Taiwan SMART1(33): M07 | 3 x 3  | 0.81                               | 0.66  | 1.45        | 1.27  |
|                        | 20 x 3 | 8.90                               | 10.08 | 9.08        | 10.83 |
| Taiwan SMART1(33): I01 | 3 x 3  | 1.56                               | 1.77  | 1.37        | 1.51  |
|                        | 20 x 3 | 12.29                              | 13.25 | 9.96        | 10.84 |

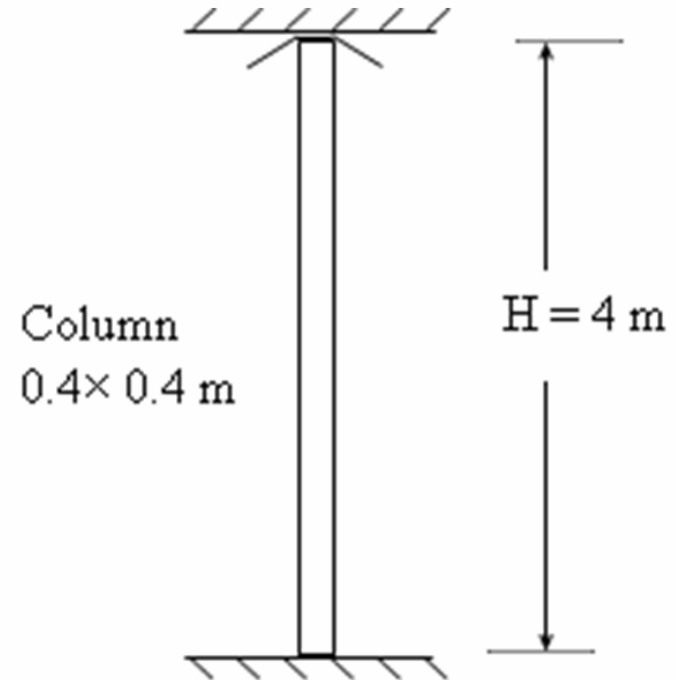


## Results

- For stiffer building, of the same height, the contribution of rotation will be greater
- For **squat building** the rotation effects fluctuate within the range of uncertainties connected to earthquake motions, and thus are of **little concern**
- The contribution of **vibration modes** higher than the first is minor
- **Higher ratio** between rotational and translational effects for **tall building** model, in some case incidence higher than 20%
- Key assumption is that soil deforms as in **free field**, without soil-structure interaction
- For Taiwan records the ratio between vertical and horizontal peaks is 0.3 - 0.5 while in other near field situation a ratio even **higher than 1** has been observed,

## Local effects

- Only one element assumed for columns between two stories and beams within a single bay
- Local effects, in which columns or beams vibrate along the span, thus disregarded
- Possible vibrations of columns can be investigated with simple structural model that highlight the effect of high frequency part of rotational response spectrum
- To relevant peak accelerations, correspond small peak displacement and thus tiny resultant stress



➤ From a structural point of view, if a vertical motion different from point to point is superposed to a rigid translation of the soil, there are **two possible consequences**

1. *High frequency vibration along beams and columns*
2. *Overall rotation of the base of the structure*

➤ First effect capable to provide huge local accelerations, but meaningless for resistance of the structure

➤ **Stress** due to the second effect tends to increase with the building height and with the stiffness of the building

➤ If the plane dimensions are comparable to the building height, rotations effects can be disregarded

➤ For relatively tall buildings having ratios of height to plan dimensions around 3 or more rotations in near field should not be disregarded

Thank you for your attention